

Journal Publications

† indicates equal contribution, and * indicates corresponding author.

1. Meiyuan Zou[†], Jiajie Yu[†], Yong Lv, Bo Lu*, **Wenzheng Chi***, and Lining Sun, "A Novel Day-to-Night Obstacle Detection Method for Excavators based on Image Enhancement and Multi-sensor Fusion," *IEEE Sensors Journal*, 2023, Early Access.
2. Yang Hong, Zhiyu Ding, Yuan Yuan, **Wenzheng Chi***, and Lining Sun, "Obstacle Avoidance Learning for Robot Motion Planning in Human-Robot Integration Environments," *IEEE Transactions on Cognitive and Developmental Systems*, 2023, Early Access.
3. Yuan Yuan, Jie Liu, **Wenzheng Chi***, Guodong Chen*, and Lining Sun*, "A Gaussian Mixture Model based Fast Motion Planning Method Through Online Environmental Feature Learning," *IEEE Transactions on Industrial Electronics*, 2023, 70(4): 3955-3965.
4. Songlin Wei, Guodong Chen*, **Wenzheng Chi***, Zhenghua Wang, and Lining Sun, "Object Clustering with Dirichlet Process Mixture Model for Data Association in Monocular SLAM," *IEEE Transactions on Industrial Electronics*, 2023, 70(1): 594-603.
5. Zhiyu Ding[†], Jie Liu[†], **Wenzheng Chi***, Jiankun Wang, Guodong Chen, Lining Sun, "PRTIRL Based Socially Adaptive Path Planning for Mobile Robots," *International Journal of Social Robotics*, 2022, Early Access.
6. Jie Liu[†], Yong Lv[†], Yuan Yuan, **Wenzheng Chi***, Guodong Chen, and Lining Sun, "An Efficient Robot Exploration Method based on Heuristics Biased Sampling," *IEEE Transactions on Industrial Electronics*, 2022, Early Access.
7. Jiankun Wang[†], **Wenzheng Chi***, Chenming Li, Max Q.-H. Meng*, "Efficient Robot Motion Planning Using Bidirectional-Unidirectional RRT Extend Function," *IEEE Transactions on Automation Science and Engineering*, 2022, 19(3): 1859 - 1868.
8. **Wenzheng Chi**, Zhiyu Ding, Jiankun Wang*, Guodong Chen*, and Lining Sun*, "A Generalized Voronoi Diagram based Efficient Heuristic Path Planning Method for RRTs in Mobile Robots," *IEEE Transactions on Industrial Electronics*, 2022, 69(5): 4926-4937. (2022 ESI Highly Cited Papers)
9. **Wenzheng Chi**[†], Jiankun Wang[†], Zhiyu Ding, Guodong Chen*, and Lining Sun*, "A Reusable Generalized Voronoi Diagram Based Feature Tree for Fast Robot Motion Planning in Trapped Environments," *IEEE Sensors Journal*, 2022, 22(18): 17615 - 17624.
10. Yong Lv, Jie Liu, **Wenzheng Chi***, Guodong Chen, and Lining Sun, "An Inverted Residual based Lightweight Network for Object Detection in Sweeping Robots," *Applied Intelligence*, 2022, 52: 12206-12221.
11. Jie Liu, Chaoqun Wang, **Wenzheng Chi***, Guodong Chen, and Lining Sun, "Estimated Path Information Gain-based Robot Exploration under Perceptual Uncertainty," *Robotica*, 2022, 40(8): 2748-2764.
12. Jiankun Wang, Jianbang Liu, Weinan Chen, **Wenzheng Chi**, Max Q.-H. Meng*, "Robot Path Planning via Neural-Networks-Driven Prediction," *IEEE Transactions on Artificial Intelligence*, 2022, 3(3): 451 - 460.
13. Zheng Wang, Hui Xu, Na Lv, Wei Tao*, Guodong Chen, **Wenzheng Chi***, and Lining Sun, "Dynamic Obstacle Avoidance for Application of Human-Robot Cooperative Dispensing Medicines," *Journal of Shanghai Jiaotong University (Science)*, 2022, 27: 24-35.
14. Dong Li, Yulin Fan, Na Lv, Guodong Chen, Zheng Wang, and **Wenzheng Chi**, "Safety Protection Method of Rehabilitation Robot Based on fNIRS and RGB-D Information Fusion," *Journal of Shanghai Jiaotong University (Science)*, 2022, 27: 45-54.
15. Yong Lv, Yuemei Fang, **Wenzheng Chi***, Guodong Chen*, and Lining Sun*, "Object Detection for Sweeping Robots in Home Scenes (ODSR-IHS): a Novel Benchmark Dataset," *IEEE Access*, 2021, 9: 17820-17828.
16. Zixiang Wang, Shuxin Xie, Guodong Chen*, **Wenzheng Chi***, Zihao Ding, and Peng Wang, "An Online Flexible Sorting Model for Coal and Gangue Based on Multi-Information Fusion," *IEEE Access*, 2021, 9: 90816-90827.
17. Jiankun Wang, **Wenzheng Chi**, Chenming Li, Chaoqun Wang, Max Q.-H. Meng*, "Neural RRT*: Learning-based Optimal Path Planning," *IEEE Transactions on Automation Science and Engineering*, 2020, 17(4): 1748 - 1758. (2021 ESI Highly Cited Papers)
18. Peng Wang, Yulin Fan, Guodong Chen*, **Wenzheng Chi***, Zhenhua Wang, and Lining Sun, "Design and Analysis of Full-scale Scanning System for Curved Glass based on Motion and 3D Features," *Applied Optics*, 2020, 59(29): 9195-9205.

19. Zihao Ding, Guodong Chen*, Zheng Wang, **Wenzheng Chi***, Zhenhua Wang, and Yulin Fan, "A Real-Time Multilevel Fusion Recognition System for Coal and Gangue Based on Near-Infrared Sensing," *IEEE Access*, 2020, 8: 178722-178732.
20. Zihao Ding[†], Hui Xu[†], Guodong Chen, Zheng Wang*, **Wenzheng Chi***, Heng Zhang, Zhenhua Wang, Lining Sun, Guilin Yang, and Yifang Wen, "Three-dimensional Reconstruction Method based on Bionic Active Sensing in Precision Assembly," *Applied Optics*, 2020, 59(3): 846-856.
21. **Wenzheng Chi**, Chaoqun Wang, Jiankun Wang, and Max Q.-H. Meng*, "Risk-DTRRT-Based Optimal Motion Planning Algorithm for Mobile Robots," *IEEE Transactions on Automation Science and Engineering*, 2019, 16(3): 1271-1288.
22. Chaoqun Wang, Jiyu Cheng, **Wenzheng Chi**, Tingfang Yan*, and Max Q.-H. Meng*, "Autonomous Robotic Exploration by Incremental Road Map Construction," *IEEE Transactions on Automation Science and Engineering*, 2019, 16(4): 1720-1731.
23. Chaoqun Wang, **Wenzheng Chi**, Yuxiang Sun, and Max Q-H Meng*, "Semantic-aware Informative Path Planning for Efficient Object Search Using Mobile Robot," *IEEE Transactions on Automation Science and Engineering*, 2019, 51(8): 5230 - 5243.
24. Jiankun Wang, **Wenzheng Chi**, Mingjie Shao, and Max Q.-H. Meng*, "Finding a High-Quality Initial Solution for the RRTs Algorithms in 2D Environments," *Robotica*, 2019, 37(10): 1677-1694.
25. Renzheng Zhang[†], Guodong Chen[†], Zheng Wang*, **Wenzheng Chi***, Zhenhua Wang, Lining Sun, Guilin Yang, and Yifang Wen, "Multi-color Space Learning for Image Segmentation based on a Support Vector Machine," *OSA Continuum*, 2019, 2(11): 3050-3065.
26. **Wenzheng Chi**, Jiaole Wang, and Max Q.-H. Meng*, "A Gait Recognition Method for Human Following in Service Robots," *IEEE Transactions on Systems, Man, and Cybernetics-Systems*, 2018, 48(9): 1429-1440.

Conference Publications

1. Songlin Wei, Guodong Chen*, **Wenzheng Chi***, Zhenhua Wang, and Lining Sun, "3D Object Aided Self-Supervised Monocular Depth Estimation," *2022 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*, 2022, pp. 10635-10642.
2. Dingfeng Chen, Qingchuan Xu, Jie Liu, Meiyuan Zou, **Wenzheng Chi***, and Lining Sun, "A Generalized Voronoi Diagram based Robot Exploration Method for Mobile Robots," *2022 IEEE International Conference on Robotics and Biomimetics (ROBIO)*, 2022, pp. 1029-1035.
3. Yuqi Kong, Yao Wang, Yang Hong, Rongguang Ye, **Wenzheng Chi***, and Lining Sun, "A Generative Adversarial Network Based Motion Planning Framework for Mobile Robots in Dynamic Human-Robot Integration Environments," *2022 14th International Conference on Social Robotics (ICSR)*, 2022, pp. 427-439.
4. Yao Wang, Yuqi Kong, Zhiyu Ding, **Wenzheng Chi***, and Lining Sun, "NRTIRL Based NN-RRT* Path Planner in Human-Robot Interaction Environment," *2022 14th International Conference on Social Robotics (ICSR)*, 2022, pp. 496-508.
5. Meiyuan Zou[†], Qingchuan Xu[†], Jianfeng Bian, Dingfeng Chen, **Wenzheng Chi***, and Lining Sun, "An Efficient Medicine Identification and Delivery System based on Mobile Manipulation Robot," *2022 14th International Conference on Social Robotics (ICSR)*, 2022, pp. 417-426.
6. Kang Song, Yueyuan Zhang*, Bo Lu, **Wenzheng Chi**, and Lining Sun, "UAV Forest Fire Detection based on RepVGG-YOLOv5," *2022 IEEE International Conference on Robotics and Biomimetics (ROBIO)*, 2022, pp. 1277-1282.
7. Meiyuan Zou, Jiajie Yu, Bo Lu, **Wenzheng Chi***, and Lining Sun, "Active Pedestrian Detection for Excavator Robots based on Multi-Sensor Fusion," *2022 IEEE International Conference on Real-time Computing and Robotics (RCAR)*, 2022, pp. 255-260.
8. Qingchuan Xu, Yang Hong, Yueyuan Zhang, **Wenzheng Chi***, and Lining Sun, "Grounding Language to Natural Human-robot Interaction in Robot Navigation Tasks," *2021 IEEE International Conference on Robotics and Biomimetics (ROBIO)*, 2021, pp. 352-357.
9. Rongguang Ye, Qingchuan Xu, Jie Liu, Yang Hong, Chengfeng Sun, **Wenzheng Chi***, and Lining Sun, "A Natural Language Instruction Disambiguation Method for Robot Grasping," *2021 IEEE International Conference on Robotics and Biomimetics (ROBIO)*, 2021, pp. 601-606.
10. Jianbang Liu, Baopu Li, Tingguang Li, **Wenzheng Chi**, Jiankun Wang*, and Max Q.-H. Meng*, "Learning-based Fast Path Planning in Complex Environments," *2021 IEEE International Conference on Robotics and Biomimetics (ROBIO)*, 2021, pp. 1351-1358.

11. Jie Liu, Yong Lv, Yuan Yuan, **Wenzheng Chi***, Guodong Chen*, and Lining Sun*, "A Prior Information Heuristic based Robot Exploration Method in Indoor Environment," *2021 IEEE International Conference on Real-time Computing and Robotics (RCAR)*, 2021, pp. 129-134. **(Best Student Paper Award)**
12. Yuan Yuan, Jie Liu, Jiankun Wang, **Wenzheng Chi***, Guodong Chen*, and Lining Sun*, "A Knowledge-based Fast Motion Planning Method through Online Environmental Feature Learning," *2021 IEEE International Conference on Robotics and Automation (ICRA)*, 2021, pp. 8309-8315.
13. Yi Zhan, Zihao Wang, Jiarui Xu, Guoyi Yu, Fengwei An, **Wenzheng Chi**, and Chao Wang, "Fast CORDIC based Generalized-Voronoi-Diagram Hardware Accelerator for Efficient Robotic Exploration," *2020 5th International Conference on Robotics and Automation Engineering (ICRAE)*, 2020, pp. 100-105.
14. Jiyu Cheng, Yuxiang Sun, **Wenzheng Chi**, Chaoqun Wang, Hu Cheng, and Max Q.-H. Meng*, "An Accurate Localization Scheme for Mobile Robots using Optical Flow in Dynamic Environments," *2018 IEEE International Conference on Robotics and Biomimetics (ROBIO)*, 2018, pp. 723-728.
15. Kuanqi Cai, **Wenzheng Chi**, and Max Q.-H. Meng*, "A Vision-based Road Surface Slope Estimation Algorithm for Mobile Service Robots in Indoor Environments," *2018 IEEE International Conference on Information and Automation (ICIA)*, 2018, pp. 621-626.
16. Jiankun Wang, Xintong Li, **Wenzheng Chi**, and Max Q.-H. Meng*, "Tropistic RRT*: An Efficient Planning Algorithm via Adaptive Restricted Sampling Space," *2018 IEEE International Conference on Information and Automation (ICIA)*, 2018, pp. 1639-1646.
17. **Wenzheng Chi**, Jiankun Wang, and Max Q.-H. Meng*, "Risk-Informed-RRT*: A Sampling-based Human-friendly Motion Planning Algorithm for Mobile Service Robots in Indoor Environments," *2018 IEEE International Conference on Information and Automation (ICIA)*, 2018, pp. 1101-1106.
18. **Wenzheng Chi**, and Max Q.-H. Meng*, "Risk-RRT*: A Robot Motion Planning Algorithm for the Human Robot Coexisting Environment," *2017 18th International Conference on Advanced Robotics (ICAR)*, 2017, pp. 583-588.
19. **Wenzheng Chi**, and Max Q.-H. Meng*, "A Human-friendly Robot Navigation Algorithm using the Risk-RRT Approach," *2016 IEEE International Conference on Real-time Computing and Robotics (RCAR)*, 2016, pp. 227-232. **(Best Student Paper Award)**
20. **Wenzheng Chi**, Jiaole Wang, and Max Q.-H. Meng*, "Person Verification based on Skeleton Biometrics by RGB-D Camera," *2014 IEEE International Conference on Robotics and Biomimetics (ROBIO)*, 2014, pp. 671-676.
21. **Wenzheng Chi**, Wei Zhang*, Jason Gu, and Hongliang Ren, "A Vision-based Mobile Robot Localization Method," *2013 IEEE International Conference on Robotics and Biomimetics (ROBIO)*, 2013, pp. 2703-2708.
22. **Wenzheng Chi**, Max Q.-H. Meng*, and Xijun Chen, "Robot Aided Object Segmentation based on Kinect without Prior Knowledge," *2012 IEEE International Conference on Robotics and Biomimetics (ROBIO)*, 2012, pp. 1784-1788.